

Rockwell ControlLogix Programmer Certification Practice Test (Sample)

Study Guide



Everything you need from our exam experts!

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SAMPLE

Questions

- 1. What is the primary purpose of a Continuous Task within a Logix Designer project?**
 - A. Execute periodically based on a timer**
 - B. Run once and exit**
 - C. Run continuously without interruption**
 - D. Process specific event triggers**
- 2. In a ladder logic program, what signifies that an I/O point is already assigned?**
 - A. A light indicator**
 - B. A darker gray display**
 - C. A warning message**
 - D. A different symbol**
- 3. Which feature is primarily used to identify faults in a ControlLogix system?**
 - A. Fault detection system**
 - B. Diagnostics Indicators**
 - C. Logix Monitor**
 - D. Fault History Log**
- 4. Which mode enables remote testing without disrupting the live system?**
 - A. Run Mode**
 - B. Remote Test Mode**
 - C. Program Mode**
 - D. Monitoring Mode**
- 5. Which diagnostic feature senses that the field wiring is disconnected or has been removed in a 1756 digital input module?**
 - A. Open wire detection**
 - B. No Load Detection**
 - C. Field Power Loss Detection**
 - D. Short Circuit Detection**

- 6. Which LED on a 1756 digital I/O module indicates the on/off conditions of a field device?**
- A. Module status**
 - B. I/O status**
 - C. Fault status**
 - D. Fuse status**
- 7. What does XIC look for in ladder logic programming?**
- A. A bit that is set (1), regardless of any physical device type**
 - B. A bit that is reset (0), depending on the physical device type**
 - C. A specific memory location for output**
 - D. A temporary variable in the program**
- 8. Which function does the SBR instruction serve in a programming environment?**
- A. Start/run a routine**
 - B. Jump to a specified label in the code**
 - C. Branch a section of code**
 - D. Stop a current routine execution**
- 9. Which type of output module is designed to provide electronic fusing?**
- A. 1756-OB32**
 - B. 1756-OB32E**
 - C. 1756-OF8**
 - D. 1756-IF8**
- 10. What operation allows controlling the process while allowing monitoring or editing from a remote computer?**
- A. Program Mode**
 - B. Remote Mode**
 - C. Test Mode**
 - D. Run Mode**

Answers

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1. C
2. B
3. B
4. B
5. A
6. B
7. A
8. C
9. B
10. B

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Explanations

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1. What is the primary purpose of a Continuous Task within a Logix Designer project?

- A. Execute periodically based on a timer**
- B. Run once and exit**
- C. Run continuously without interruption**
- D. Process specific event triggers**

The primary purpose of a Continuous Task within a Logix Designer project is to run continuously without interruption. Continuous tasks are designed to execute in a cyclic manner, effectively allowing the associated program to continuously perform its operations as long as the controller is running. This makes them essential for real-time processes where ongoing monitoring and control are necessary, such as in systems that require constant input handling or data processing without any delays. In this task type, the program would typically operate at the highest priority level, ensuring that critical functions are monitored and executed consistently over time. This is in stark contrast to other task types that may only run at specific intervals or under certain conditions, which are not suitable for scenarios requiring ongoing responsiveness or control.

2. In a ladder logic program, what signifies that an I/O point is already assigned?

- A. A light indicator**
- B. A darker gray display**
- C. A warning message**
- D. A different symbol**

In ladder logic programming, a darker gray display signifies that an I/O point is already assigned. This visual indication allows programmers to quickly identify which input or output elements are already mapped or used within the program. The use of color coding, such as darker shades, helps improve readability and aids in the efficient design of the program, allowing for easier troubleshooting and maintenance. Other methods, such as warning messages or specific symbols, may provide information on various issues or requirements within the program but do not specifically indicate assignment status in the same clear manner. The visual cues through color differentiation are a standard convention in many programming environments, particularly in ControlLogix, to convey important information at a glance.

3. Which feature is primarily used to identify faults in a ControlLogix system?

- A. Fault detection system**
- B. Diagnostics Indicators**
- C. Logix Monitor**
- D. Fault History Log**

The Diagnostics Indicators feature plays a crucial role in identifying faults within a ControlLogix system. These indicators provide real-time visual information about the status of the controller and its peripherals. Located on hardware components such as the processor, modules, and power supplies, the indicators can signal various conditions, including faults, normal operation, and diagnostics statuses. When a fault occurs, the Diagnostics Indicators help users quickly identify the type and location of the issue, allowing for faster troubleshooting and maintenance. This immediate feedback is essential for operators and engineers, making it easier to maintain system integrity and operational efficiency. While other options, like the Fault History Log, also provide valuable information regarding previous faults, they are not as immediate or clear as the real-time visual cues provided by the Diagnostics Indicators. This makes the Diagnostics Indicators the primary feature for immediate fault identification in a ControlLogix system.

4. Which mode enables remote testing without disrupting the live system?

- A. Run Mode**
- B. Remote Test Mode**
- C. Program Mode**
- D. Monitoring Mode**

Remote Test Mode is designed specifically for conducting tests on a control system while it remains operational, ensuring that real-time processes are not interrupted. This is particularly important in industrial environments where even a brief disruption can lead to costly downtimes or safety hazards. In Remote Test Mode, engineers can simulate inputs, monitor outputs, and validate the behavior of control logic without affecting the ongoing production processes. This allows for thorough testing and troubleshooting from a remote location, facilitating maintenance and updates without disturbing the live system. By having this capability, operators can confidently implement changes or verify system behavior in a controlled environment, leading to improved efficiency and reliability in manufacturing or process control scenarios.

5. Which diagnostic feature senses that the field wiring is disconnected or has been removed in a 1756 digital input module?

A. Open wire detection

B. No Load Detection

C. Field Power Loss Detection

D. Short Circuit Detection

The correct answer is the feature known as Open Wire Detection. This diagnostic capability is specifically designed to identify when there is a disconnection in the field wiring associated with a digital input module, such as the 1756. Open Wire Detection monitors the integrity of the electrical connection; when a wire that connects the input module to the field device (like a sensor or switch) becomes disconnected, this feature will recognize that the expected signal is missing and indicate a fault condition. This is crucial for ensuring system reliability and safety, as disconnected wires can lead to false readings or complete loss of input data, affecting process control. By providing an early warning about such disconnections, it allows for proactive maintenance and troubleshooting. The other options, while they address different aspects of electrical connectivity and safety, do not specifically pertain to detecting open circuits in field wiring. For instance, No Load Detection refers to sensing conditions where no load is present, which does not specifically imply a disconnection. Field Power Loss Detection monitors for loss of power to the field devices, and Short Circuit Detection indicates a fault condition caused by wires being shorted together, rather than open circuits. Each of these features plays a role in overall system diagnostics, but Open Wire Detection is specifically focused on identifying

6. Which LED on a 1756 digital I/O module indicates the on/off conditions of a field device?

A. Module status

B. I/O status

C. Fault status

D. Fuse status

The I/O status LED on a 1756 digital I/O module is designed specifically to indicate the on/off conditions of field devices connected to that particular module. When a field device is active and receiving power, the I/O status LED will light up or change its state, providing a visual representation of that device's operational state. This functionality is essential for troubleshooting and monitoring, as it allows an operator to quickly ascertain whether a device is functioning as expected. The module status LED generally signals the overall operational status of the module itself, while the fault status LED indicates whether there are any malfunctions or errors within the module. The fuse status would pertain to the condition of a protective fuse within the module, if applicable. These other LEDs serve different purposes and do not provide specific feedback regarding the individual state of the field devices connected to the I/O module.

7. What does XIC look for in ladder logic programming?

- A. A bit that is set (1), regardless of any physical device type**
- B. A bit that is reset (0), depending on the physical device type**
- C. A specific memory location for output**
- D. A temporary variable in the program**

The XIC (Examine if Closed) instruction in ladder logic programming is used to evaluate the status of a boolean condition, specifically looking for a bit that is set to 1. When the XIC instruction encounters a bit set to 1, it allows the rung in which it is contained to be true, enabling any output or subsequent conditions on that rung. This function is fundamental in control systems, as it helps determine when certain outputs should be activated based on the status of inputs or bits in memory. The XIC instruction effectively checks alongside physical devices and internal memory locations to ensure that the correct actions are taken in response to desired conditions being met. Other options mention conditions or types of bits that do not apply to the specific function of the XIC instruction. For instance, the XIC does not focus on bits being reset or temporary variables. Instead, it directly examines bits that indicate an On (1) condition, reinforcing its role in ensuring that processes are controlled correctly based on input signals.

8. Which function does the SBR instruction serve in a programming environment?

- A. Start/run a routine**
- B. Jump to a specified label in the code**
- C. Branch a section of code**
- D. Stop a current routine execution**

The SBR instruction, or Subroutine Branch instruction, is designed to branch a section of code within a programming environment. This instruction allows a programmer to direct the flow of execution to a specific segment of code, enabling modular programming practices. By using SBR, chunks of code can be reused without having to duplicate them throughout the program. Branching with the SBR instruction typically facilitates clearer organization of code, as it separates different functional areas or tasks. This modular approach enhances readability and maintainability, allowing for easier updates and troubleshooting. The ability to branch to various sections of the program contributes to more efficient program execution by optimizing code logic and flow. In contrast, starting or running a routine is indicative of initiating program behavior, which does not align with the primary function of SBR. Jumping to a specified label might suggest a direct transfer of control, commonly associated with jump or branch instructions in various contexts but not specifically with the SBR functionality. Stopping a current routine execution would be contrary to the purpose of the SBR instruction, which is to facilitate continued program operation by branching to another section rather than halting it.

9. Which type of output module is designed to provide electronic fusing?

- A. 1756-OB32**
- B. 1756-OB32E**
- C. 1756-OF8**
- D. 1756-IF8**

The 1756-OB32E output module is specifically designed to provide electronic fusing, which is a critical feature for enhancing system reliability and safety. This type of module incorporates electronic overload protection that helps to prevent damage to both the output device and the module itself in case of an overload situation. Unlike traditional fuses, which require physical replacement after they blow, electronic fusing allows the output to be reset without the need for manual intervention, thereby reducing maintenance time and preventing downtime. The 1756-OB32 and other options do not include this electronic fusing feature, which is significantly beneficial for applications requiring a high degree of uptime and reliability. Thus, the 1756-OB32E offers a more advanced solution tailored to modern automation needs where electronic protection mechanisms are favored.

10. What operation allows controlling the process while allowing monitoring or editing from a remote computer?

- A. Program Mode**
- B. Remote Mode**
- C. Test Mode**
- D. Run Mode**

The operation that facilitates controlling a process while allowing monitoring or editing from a remote computer is Remote Mode. This mode enables operators and engineers to interact with the ControlLogix system from a distance, providing the ability to make adjustments, monitor performance, and troubleshoot issues without needing to be physically present at the control panel or system location. In Remote Mode, a user can access the control system through network connections, such as Ethernet, enabling real-time data exchange, updates, and modifications to control parameters. This remote access is essential for maintaining efficiency, especially in large facilities or when managing multiple systems spread over vast areas. In contrast, other modes such as Program Mode, Test Mode, and Run Mode focus primarily on either setting up the system, testing specific configurations, or executing pre-defined processes without the flexibility of remote interaction. Specifically, Program Mode is intended for developing and modifying code, Test Mode is often used for verifying the functionality of the logic under controlled conditions, and Run Mode executes the logic as it was designed without allowing modifications. Therefore, Remote Mode stands out as the option that specifically offers remote control capabilities in the system.